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# EUROPEAN PATENT OFFICE

## Patent Abstracts of Japan

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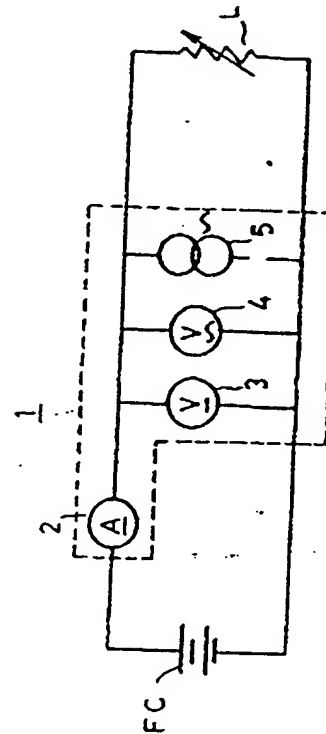
APPLICATION DATE : 20-05-83  
APPLICATION NUMBER : 58089481

APPLICANT : SANYO ELECTRIC CO LTD;

INVENTOR : WASHIMI SHINGO;

INT.CL. : H01M 8/04 G05D 23/19

TITLE : TEMPERATURE CONTROL DEVICE OF  
FUEL CELL

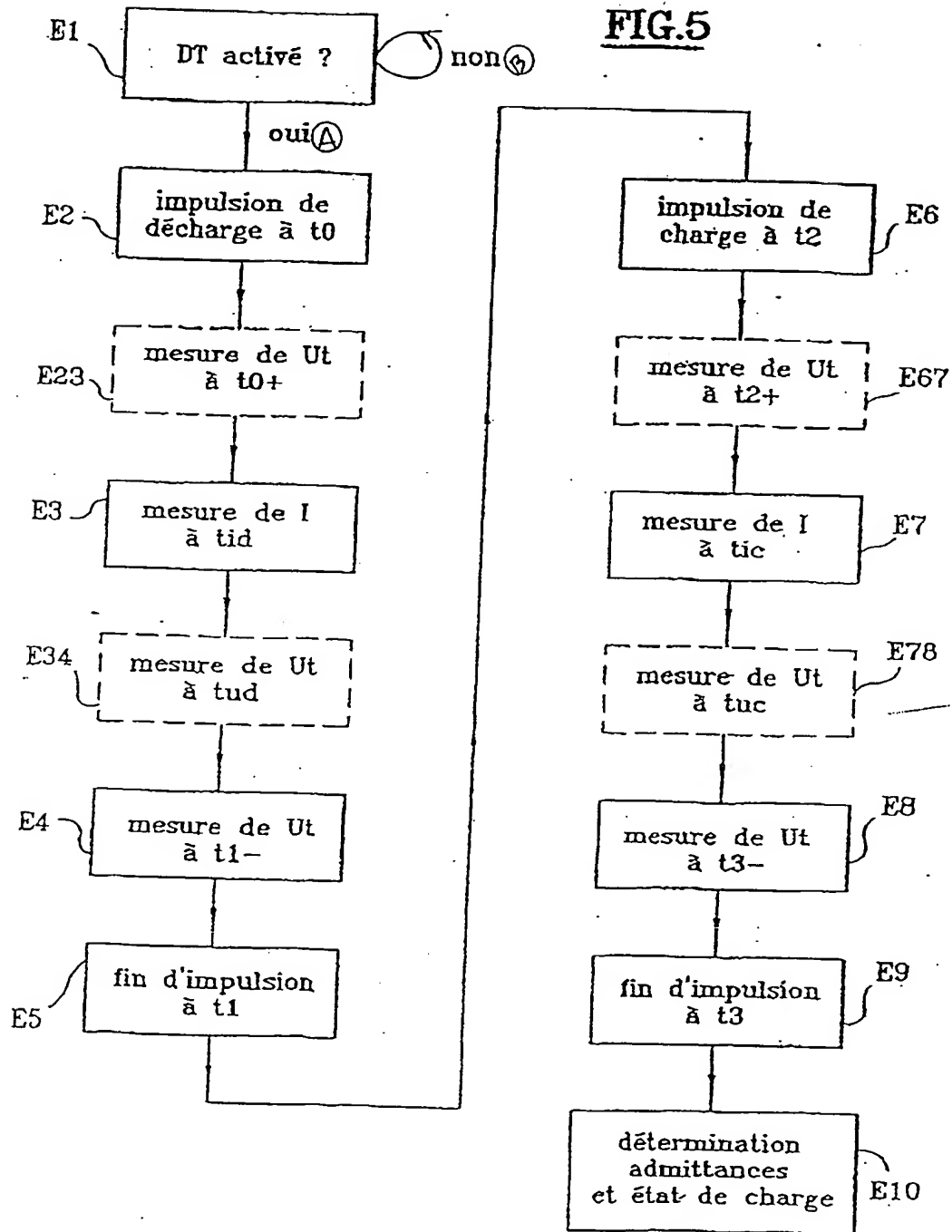


ABSTRACT : PURPOSE: To detect the cell temperature from outside by measuring the internal impedance of a cell.

CONSTITUTION: An impedance measuring device 1 is connected between a fuel cell FC and a load L and is composed of a DC ammeter 2, a DC voltmeter 3, an AC voltmeter 4, and a constant-frequency, constant-current AC generator 5. The AC generator 5 feeds currents in parallel to the cell FC and the DC load L, and the AC voltage displayed on the AC voltmeter 4 is generated by the resultant impedance  $Z_r$  of the internal impedance  $Z$  of the fuel cell FC and the load resistance  $R$ . Accordingly, individual detection signals from the impedance measuring device 1 are inputted to a control unit 6 to calculate the internal impedance  $Z$  of the cell. The value of this  $Z$  depends on the cell temperature, thereby this  $Z$  is used as an output signal to regulate a damper 7 and a blower 8 so as to control the feed air temperature and air quantity.

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**FIG.5**



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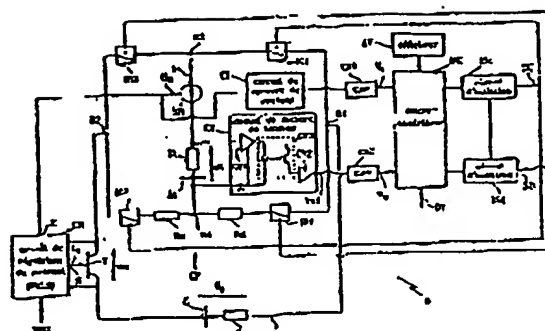
PROCESS AND DEVICE FOR MEASURING THE CHARGE STATE OF A BATTERY

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[Abstract]

The charge state of battery ( $A_t$ ) is measured using the following steps when the charge state is high: a constant charging current pulse is applied to the battery, and voltage ( $U_t$ ) across the terminals of the battery is measured for at least one predetermined time during the charging current pulse. The charge state of the battery is measured regardless of level using the following additional steps: a constant discharging current pulse is applied to the battery, and voltage ( $U_t$ ) across the terminals of the battery is measured for at least one predetermined time during the discharging current pulse.

The charge state of a battery is evaluated even when the admittance characteristics of the latter are not injective.



Key: CI Current measurement circuit  
 AF Display device  
 MC Microcontroller  
 ISc, ISd Isolation circuit  
 CV Voltage measurement circuit  
 CR Current regulating circuit (Figure 3)

The present invention relates to a process for measurement of the charge state of a battery and to a device for implementation of the process. More specifically, the present invention relates to measurement of the charge state by applying pulsed stress to the battery.

The patent application FR-A-2 685 780 discloses a process for measurement of the charge state of an electrochemical generator which applies a constant voltage pulse to a battery in order to deliver a discharging current. Measurement of said discharging current is done immediately before the end of the pulse, which makes it possible to deduce the admittance of the battery and its charge state. However, this process can only be applied to cases where the internal admittance characteristic of the battery as a function of the charge state is injective, that is, a single charge state corresponds to a certain admittance. This only occurs for low charge state levels. For high charge states, it is not possible to evaluate the charge state of a battery by this process.

Furthermore, in practice, the curve characterizing the admittance of a battery as a function of its charge state is roughly linear for low charge states but bends for higher charge states. In Figure 1, curve Cdch is an example admittance characteristic as a function of the charge state of a nickel-cadmium battery obtained by applying a discharging current to the battery. The admittance, besides the non-bijective character of its characteristic, has low sensitivity to charge states higher than 60%, which means the evaluation of the charge state by means of a discharging current is not very precise.

The purpose of the present invention is to solve the aforementioned problems by providing a process and a device for measuring the charge state of a battery, which are more precise for high charge states and which can be used regardless of pulsed current.

For this purpose, a process for measuring the charge state of a battery is characterized by the fact that it includes the following successive steps:

- a constant charging current pulse is applied to said battery, and
- the voltage across the terminals of said battery is measured for at least one predetermined time during said charging current pulse.

The admittance characteristic as a function of the charge state obtained by applying a charging current to the battery, as shown by the curve Cch of Figure 1, is much more sensitive to high charge states, that is, greater than 60% in the case of a nickel-cadmium battery, than the admittance curve obtained with a discharging current.

The process according to the invention also relates to measuring the charge state of a battery for any pulsed current through the battery, regardless of the level of the charge state.

Thus, the process also includes the following successive steps:

- a constant discharging current pulse is applied to said battery, and
- the voltage across the terminals of said battery is measured for at least one predetermined time during said discharging current pulse.

The use of the two admittance characteristics, for a charging current and a discharging current, makes it possible to eliminate the ambiguity due to the non-bijective nature of these two curves.

In order to determine the response of the battery to the charging pulse, the step of measuring the voltage across the terminals of the battery during the charging pulse can be performed at a time immediately before the end of said charging pulse.

In a similar manner, the step of measuring the voltage across the terminals of the battery during the discharging pulse can be performed at a time immediately before the end of said discharging pulse.

In order to evaluate the admittance of the battery for a charging current, the process can include a step for measuring the current passing through the battery at a time close to the midpoint between the beginning and end of said charging pulse.

Likewise, the process can include a step for measuring the current passing through the battery at a time close to the midpoint between the beginning and end of said discharging pulse.

It is also desirable to be able to verify experimentally the theoretical voltage response of the battery for a constant charging current pulse. Steps can then be provided for measuring the voltage across the terminals of the battery at a time immediately after the beginning of said

charging pulse and at a time close to the midpoint between the beginning and end of said charging pulse.

In a comparable manner, the process can include steps for measuring the voltage across the terminals of the battery at a time immediately after the beginning of said discharging pulse and at a time close to the midpoint between the beginning and end of said discharging pulse.

A device for implementing the process according to the invention, for measuring the charge state of a battery to be tested by means of an auxiliary generator, is characterized by the fact that it includes

- a means for applying a charging current pulse to said battery from said auxiliary generator,
- a means for regulating the current passing through the battery to a constant value in order to assert a constant current on the battery during said charging pulse, and
- a means for measuring the voltage across the terminals of the battery for at least one predetermined time during said charging pulse.

The device can also include a means for applying a discharging current pulse to the battery from said auxiliary generator. The regulating means then asserts a constant current on the battery during said discharging pulse. The measuring means measures the voltage across the terminals of the battery for at least one predetermined time during said discharging pulse.

The auxiliary generator powers a bridge circuit formed by four lateral branches and a diagonal branch. The diagonal branch includes the battery. A first lateral branch includes a first switch. A second lateral branch includes a second switch and a discharging resistor. A third lateral branch includes a third switch and a charging resistor. A fourth lateral branch includes a fourth switch. The first and third lateral branches form said means for applying a charging current pulse to the battery from said auxiliary generator and they carry a current along with said diagonal branch only during a charging pulse. The second and fourth lateral branches form said means for applying a discharging current pulse to the battery from said auxiliary generator and they carry a current along with said diagonal branch only during a discharging pulse.

Typically, said means for regulating the current passing through the battery includes a Hall probe that is connected in series with the battery and that produces an output voltage depending on the current passing through the battery, a regulating circuit that receives the output voltage from the Hall probe, and a transistor that is connected in series with the auxiliary generator and whose base current is controlled by the regulating circuit in response to the variations of the current passing through the battery.

In order to regulate the current passing through the battery during the charging pulses and the discharging pulses, that is, independent of the current direction through the battery, the

regulating circuit can include at its input a rectifying circuit producing an output voltage equal to the absolute value of the output voltage of said Hall probe.

The regulating circuit can include an optoelectronic isolator, so as to isolate galvanically the means for measuring the voltage in the regulating circuit and the power circuit including the battery and the auxiliary generator.

Also for the purpose of isolation, the means for measuring the voltage across the terminals of the battery can include at least one optoelectronic isolator.

The device can also include a means, preferably galvanically isolated from the battery and from the auxiliary generator, for measuring the current passing through the battery.

Other characteristics and advantages of the present invention will appear more clearly upon reading the following description of several preferred embodiments of the invention in reference to the corresponding appended drawings in which:

- Figure 1 is a diagram showing two admittance curves of a nickel-cadmium battery as a function of the charge state (capacity/nominal capacity) of the latter, which are determined by respectively applying a charging current and a discharging current to the battery;
- Figure 2 is a block diagram of a device for measuring the charge state of a battery according to the invention;
- Figure 3 is a block diagram of a regulating circuit included in the measurement device of Figure 2;
- Figure 4A is a timing diagram for discharging and charging control signals delivered by a microcontroller included in the measurement device of Figure 2;
- Figure 4B is a timing diagram for the voltage response of the battery in Figure 2 to a constant discharging current pulse and to a constant charging current pulse; and
- Figure 5 is an algorithm of a process for measuring the charge state of a battery according to the present invention.

In reference to Figure 2, measurement device D for measuring the charge state of electrical battery At to be tested which has an internal impedance  $Z_t$  includes, according to a first embodiment of the invention, bridge circuit CP formed by four lateral branches and one diagonal branch, and auxiliary electrical accumulator generator G. Generator G delivers a voltage  $U_g$  that is greater than the nominal voltage of battery At and has an internal impedance  $Z_g$ . The voltage  $U_g$  is typically equal to 12 volts. The positive terminal of generator G is connected to first terminal B1 of bridge circuit CP. Second terminal B2 of bridge circuit CP is connected to the collector of NPN bipolar transistor T. The emitter of transistor T is connected to the negative terminal of auxiliary generator G.

First lateral branch B1-B3 of bridge circuit CP includes first switch IC1. Second lateral branch B1-B4 is made up of second switch ID1 and discharging resistor  $R_d$  connected in series.



Third lateral branch B2-B4 includes third switch IC2 and charging resistor  $R_c$  connected in series. Fourth lateral branch B2-B3 includes fourth switch ID2. Diagonal branch B3-B4 contains battery to be tested  $A_t$  and Hall probe SH connected in series. Switches IC1, ID1, IC2 and ID2 are MOS transistors.

Hall probe SH applies output voltage  $U_H$  to input E of current regulating circuit CR. Output S of circuit CR is directly applied to the base of transistor T.

Device D also includes microcontroller MC, whose role is to control switches IC1, ID1, IC2 and ID2 of bridge circuit CP and to sense numerical measurement data signals  $V_I$  and  $V_U$  which represent, respectively, the current flowing through battery  $A_t$  and the voltage at its terminals.

Device D generates constant charging and discharging current pulses in battery to be tested  $A_t$ .

In order to generate a charging pulse, microcontroller MC applies a charging control signal SC set to "1" to first and third switches IC1 and IC2 and discharging control signal SD set to "0" to second and fourth switches ID1 and ID2, so as to close switches IC1 and IC2 and to open switches ID1 and ID2. Current I flows from the positive terminal of auxiliary generator G, through switch IC1, Hall probe SH, battery  $A_t$ , charging resistor  $R_c$ , switch IC2 and into the collector-emitter junction of transistor T.

In order to generate a discharging pulse, microcontroller MC sets charging control signal SC to "0" and discharging control signal SD to "1", so as to open switches IC1 and IC2 and to close switches ID1 and ID2. Current I flows from the positive terminal of generator G, through switch ID1, discharging resistor  $R_d$ , battery  $A_t$ , Hall probe SH, switch ID2 and into the collector-emitter junction of transistor T.

Current I flowing through battery  $A_t$  is thus propagated in two opposite directions B3-B4 and B4-B3 in the diagonal branch of bridge circuit CP during the charging and discharging pulses, respectively, but in only one direction through transistor T, that is, from the collector to the emitter. Due to the presence of bridge circuit CP, a single current regulating circuit CR is activated for the two pulse types.

During a charging or discharging current pulse in battery  $A_t$ , the intensity of current I flowing through the battery is maintained constant by Hall probe SH, regulating circuit CR and transistor T. Hall probe SH transforms current I flowing in battery  $A_t$  into voltage  $U_H$  proportional to the intensity of current I. Voltage  $U_H$  is applied to input E of regulating circuit CR. Circuit CR provides regulating current  $I_R$  to the base of transistor T, which is dependent on voltage  $U_H$  and a positive reference voltage  $V_{ref}$ . Regulating current  $I_R$  varies in order to regulate the collector current of transistor T and thus to regulate current I flowing through the battery at a constant value  $I_0$  proportional to reference voltage  $V_{ref}$ .

Charging resistor  $R_c$  and discharging resistor  $R_d$  are chosen so that transistor T operates roughly following the middle of a segment limited by two intersecting points between the charging line of the transistor and the two axes of coordinates in the collector-current characteristic curve as a function of collector-emitter voltage  $V_{ce}$  of the transistor. The transistor is typically polarized in the saturation zone of the aforementioned characteristic curve.

Current regulating circuit CR shown in Figure 3 is a negative feedback loop containing current sensor circuit 1, subtracter 2, error correction circuit 3, adder 4, optoelectronic isolator 5 and power amplifier 6. Current sensor circuit 1 essentially includes impedance corrector 10, rectifying circuit 11 and non-inverting amplifier 12.

Output voltage  $U_H$  of Hall probe SH is applied, at input B of circuit CR, to impedance corrector 10. Impedance corrector 10, consisting of an operational amplifier with simple feedback as shown in Figure 3, provides voltage  $|U_{mes}|$  which is equal to voltage  $U_H$ . The input impedance of circuit 10 is very high so that very little current coming from Hall probe SH enters regulating circuit CR. Rectifying circuit 11 delivers a voltage  $|U_{mes}|$  equal to the absolute value of input voltage  $U_{mes}$  as output in order to make the sign of the latter voltage unnecessary. Rectifier circuit 11 thus provides amplifier 12 with a voltage which is always positive regardless of the direction of current I through battery At. Amplifier 12 amplifies voltage  $|U_{mes}|$  into a positive voltage  $V_{mes}$  which is applied to a positive input of subtracter 2.

A negative input of subtracter 2 receives reference voltage  $V_{ref}$  which is proportional to the desired current  $I_0$  to assert in battery during the charging and discharging pulses. Output signal ( $V_{mes} - V_{ref}$ ) of subtracter 2 is transmitted to error correction circuit 3. The latter is a conventional corrector of the proportional-integral type, also called PI corrector. The transfer function of the PI corrector is typically the sum of the transfer function for an inverting amplifier and the transfer function for an integrator.

The output of error correction circuit 3 is connected to adder 4 which delivers output voltage  $V_s$  equal to the sum of the output voltage of error correction circuit 3 and a predetermined positive polarization voltage  $V_{pol}$ . Voltage  $V_{pol}$  is set in such a way as to make transistor T conductive and to produce in battery At a current close to the desired current  $I_0$  to assert during the charging and discharging pulses.

The output of adder 4 is connected to optoelectronic isolator 5, and in particular to the anode of light-emitting diode D through resistor R1. The cathode of diode D is grounded. Light-emitting diode D, carrying the output current  $I_s$  of adder 4, illuminates the base-emitter junction of NPN bipolar phototransistor  $T_{ph}$ , thus creating a variable base current  $I_B$  through the base of the phototransistor which depends on current  $I_s$ . The collector of phototransistor  $T_{ph}$  is connected directly to the collector of transistor T. The emitter of transistor  $T_{ph}$  is connected to the emitter and to the base of transistor T, respectively, through resistor R2 and through power

amplifier 6. Optoelectronic isolator 5 ensures galvanic isolation between adder 4 and power amplifier 6, and therefore between input E of the feedback loop and its output produced by transistor T.

Power amplifier 6 has the role of amplifying the collector current of phototransistor Tph and producing a sufficiently high regulating current  $I_R$  through the base of transistor T. Circuit 6 contains NPN bipolar transistor T1 whose base is connected to the emitter of phototransistor Tph, whose collector is connected to the collectors of phototransistor Tph and of transistor T, and whose emitter is connected through resistor R3 to the emitter of transistor T. As a variant, power amplifier 6 has several bipolar transistors that are cascade connected to one another in the same manner as transistor T1 with respect to phototransistor Tph.

Thus, during a charging current pulse in battery At controlled by microcontroller MC, current I through the battery tends to decrease during the pulse because of the charge on the latter. Subtractor 2 then produces a negative output voltage, which increases the output voltages of error corrector 3 and of adder 4 and current  $I_B$  through the base of phototransistor Tph, and thus increases current I such that it returns to the value  $I_0$ .

Inversely, during a discharging current pulse in battery At, the current through the battery tends to increase during the pulse. Subtractor 2 then produces a positive output voltage, which decreases voltage  $V_s$  output by adder 4 and current  $I_B$  through the base of phototransistor Tph and thus decreases current I so that it returns to the value  $I_0$ .

Device D for measuring the charge state of a battery also includes current measurement circuit CI and voltage measurement circuit CV, as shown in Figure 2. Analog voltage signals output by circuits CI and CV are provided to analog-digital converters CA1 and CA2, respectively, which transform these signals into digital measurement data signals  $V_I$  and  $V_U$  which are to be accepted and processed by microcontroller MC.

Voltage measurement circuit CV produces output voltage  $V_{s1}$  equal to voltage  $U_t$  across the terminals of battery At, and galvanically isolates the battery from microcontroller MC. Circuit CV is made up, for example, of two amplifier-impedance correctors CV1 and CV2, of which the input of one is connected to battery At and the output of the other is connected to converter CA2, and of optoelectronic isolator CV3 which galvanically isolates the two amplifiers CV1 and CV2.

Current measurement circuit CI, according to a first variant, is identical to impedance corrector circuit 10 represented in Figure 3. According to a second variant, circuit CI is the same as impedance corrector 10 and voltage  $U_{mes}$  is regenerated so that it is transmitted directly to analog-digital converter CA1, as indicated in the form of a dotted line output by impedance corrector 10 in Figure 3. Finally, according to a third variant, current measurement circuit CI is eliminated, and output voltage  $U_H$  of Hall probe SH is applied directly to converter CA1. According to the three aforementioned variants, current measurement circuit CI is isolated

galvanically by Hall probe SH from the power circuit including, in particular, battery At and auxiliary generator G.

In order to completely isolate the measurement sensing and control circuits including circuits CI, CV and MC of the power circuit including, in particular, battery At and auxiliary generator G, the control of MOS switches IC1, IC2, ID1 and ID2 by microcontroller MC is preferably galvanically isolated. For this purpose, device D includes first isolation circuit ISc that galvanically isolates the microcontroller from charging switches IC1 and IC2, and second isolation circuit ISd that galvanically isolates the microcontroller from discharging switches ID1 and ID2. In each of isolation circuits ISc and ISd, for example, a transformer isolates an amplification and pulse-shaping circuit connected to the microcontroller and two amplification circuits each connected to an MOS switch.

According to a second embodiment of the device for measuring the charge state of a battery, only charging pulses are considered. In this case, lateral branches B1-B4 and B2-B3 of bridge circuit CP are eliminated, as is one of charging switches IC1 and IC2. The charging current pulses are applied by auxiliary generator G using the remaining charging switch IC1 or IC2 controlled by signal SC output by microcontroller MC.

The process for measuring the charge state of a battery according to the invention is now given in detail in reference to Figures 4A, 4B and 5.

Figure 4A is a timing diagram for the logical charging control signals SC and the discharging control signals SD. Initially, these signals are in the "0" state. In response to an exterior test triggering pulse DT input to microcontroller MC, discharging control signal SD is set to "1" at a first time  $t_0$  in order to trigger a discharging pulse of constant current  $I = I_0$  in battery At. The discharging pulse ends at a second time  $t_1$  such that  $t_1 - t_0 = 480$  ms. Signal SD is then returned to "0." At a third time  $t_2$  is chosen such that  $(t_2 - t_1)$  is roughly equal to  $(t_1 - t_0)$ , charging control signal SC is set to "1" in such a way as to trigger a charging pulse constant current  $I$  in battery At. The charging pulse lasts until the fourth time  $t_3$  which is also 480 ms from the third time  $t_2$ .

Thus, with each test triggering pulse DT, microcontroller MC starts a cycle which includes a discharging pulse followed by a charging pulse. Measurements of current  $I$  flowing through battery At and of voltage  $U_t$  across its terminals are sensed during the discharging and charging pulses. At the end of the cycle, admittance calculations are performed by the microcontroller in order to determine the charge state of the battery.

Figure 4B shows, as an example, a timing diagram of the variation of voltage  $\Delta U_t$  for voltage  $U_t$  across the terminals of the battery during the aforementioned discharging and charging pulses.

Figure 5 represents the algorithm used by microcontroller MC for measuring the charge state. In a first step E1, the microcontroller is in the standby state, waiting for test triggering pulse DT. When pulse DT activates the microcontroller, a discharging pulse is produced by setting discharging control signal SD to the "1" state in the next step E2 at time  $t_0$ . In step E3, the measurement of current  $I$  flowing through battery At is sensed at a time  $t_{id}$  between  $t_0$  and  $t_1$ , that is, during the duration of the discharging pulse. Typically,  $t_{id}$  is equal to the midpoint of  $t_0$  and  $t_1$ . The measurement of current  $I$  is obtained by sensing digital signal  $V_i$  output by analog-digital converter CA1. In step E4, voltage  $U_t$  across the terminals of the battery is measured at a time  $t_{1-}$  just before the end of the discharging pulse  $t_1$ . Typically,  $t_{1-}$  is equal to  $(t_1 - 2 \text{ ms})$ . The measurement of voltage  $U_t$  is obtained by sensing digital signal  $V_U$  output by analog-digital converter CA2. The discharging pulse is stopped by setting signal SD back to "0" in the next step E5 at time  $t_1$ . A rest period is established from time  $t_1$  until time  $t_2$ , during which signals SC and SD are "0" and no measurements are sensed.

In step E6, a charging pulse is produced by setting charging control signal SC to "1" at time  $t_2$ . A measurement of the current is sensed in the next step E7 at time  $t_{ic}$  between  $t_2$  and  $t_3$ . Preferably,  $t_{ic}$  is equal to the average of times  $t_2$  and  $t_3$ . In step E8, voltage  $U_t$  across the terminals of the battery is measured at time  $t_{3-}$  immediately before the end of the charging pulse  $t_3$ . Time  $t_{3-}$  is, for example, equal to  $(t_3 - 2 \text{ ms})$ . In step E9, charging control signal SC is set back to "0," and the charging pulse is stopped at time  $t_3$ . The cycle of sensing measurements is then complete.

In the course of a last step E10, admittance values of the battery are calculated for discharging and charging from the current and voltage values measured in steps E3, E4, E7 and E8. Associated with the admittance corresponding to the discharging, there are sometimes two charge state values in the curve  $Cdch$  describing the admittance during discharging as a function of the charge state represented in Figure 1. Likewise, there can be two distinct charge state values for the value of admittance during charging. The use of the admittance curves for both discharging and charging makes it possible to eliminate the ambiguity concerning the charge state and to evaluate this state precisely regardless of its value. The value of the charge state is displayed in step E10 by display device AF connected to microcontroller MC in device D.

According to a first variant of the algorithm shown in Figure 5, this algorithm also includes step E23 inserted between steps E2 and E3. In the course of step E23, the voltage across the terminals of the battery is measured at time  $t_{0+}$  immediately after the beginning of the discharging pulse  $t_0$ , that is, equal to  $(t_0 + 2 \text{ ms})$ , for example. Step E34 is also provided between steps E3 and E4 for measuring the voltage across the terminals of the battery at time  $t_{ud}$  which is close to the midpoint of times  $t_0$  and  $t_1$ , and which is typically equal to  $t_0 + 300 \text{ ms}$ . Additional steps E23 and E34 are not necessary for the establishment of the admittance and charge state

values, but are used to verify experimentally the behavior of the curve in terms of voltage response of the battery to a constant discharging current pulse, shown in Figure 4B.

According to a second variant, which can be combined with the first variant, the algorithm includes step E67 inserted between steps E6 and E7, and step E78 is implemented between steps E7 and E8. Step E67 consists of sensing a measurement of the voltage across the terminals of the battery at time  $t2+$  which is immediately after time  $t2$ , and which is typically equal to  $(t2 + 2 \text{ ms})$ . Another voltage value is measured in step E78 at time  $tuc$  which is close to the midpoint between  $t2$  and  $t3$ , and which is equal to  $(t2 + 300 \text{ ms})$ . Steps E67 and E78 have a similar role to that of steps E23 and E34, relating to the experimental verification of the behavior of the curve in terms of voltage response of the battery to a constant charging current pulse.

According to a third variant, corresponding to the second embodiment of the device described in the preceding, the algorithm used by the microcontroller only consists of steps E1 and E6 to E10. Only the charging current pulse is then considered, and step E10 determines the charge state of the battery preferably for high charge states, that is, states greater than 60% for a nickel-cadmium battery, as explained in the preamble of the description. Steps E67 and E78 can be used in the third variant in the same way as in the second variant.

### Claims

1. Process for measuring the charge state of battery ( $A_t$ ) characterized by the fact that it includes the following successive steps:
  - (E6) a constant charging current pulse is applied to said battery, and
  - (E8) voltage ( $U_t$ ) across the terminals of said battery is measured for at least one predetermined time ( $t3-$ ) during said charging current pulse.
2. Process according to Claim 1, wherein said step (E8) for measuring the voltage across the terminals of the battery during said charging pulse is performed at time ( $t3-$ ) immediately before the end ( $t3$ ) of said charging pulse.
3. Process according to Claim 1 or 2, which includes step (E7) for measuring current ( $I$ ) flowing through the battery at time ( $t_{ic}$ ) close to the midpoint between the beginning ( $t2$ ) and the end ( $t3$ ) of said charging pulse.
4. process according to any one of Claims 1 to 3, which includes steps (E67, E78) for measuring voltage ( $U_t$ ) across the terminals of the battery at time ( $t2+$ ) immediately following the beginning ( $t2$ ) of said charging pulse and at time ( $t_{uc}$ ) close to the midpoint between the beginning ( $t2$ ) and the end ( $t3$ ) of said charging pulse.
5. Process according to any one of Claims 1 to 4, which also includes the following successive steps:

- (E2) a constant discharging current pulse is applied to said battery, and
- (E4) voltage ( $U_t$ ) across the terminals of said battery is measured for at least one predetermined time ( $t_{1-}$ ) during said discharging current pulse.

6. Process according to Claim 5, wherein said step (E4) for measuring the voltage across the terminals of the battery during the discharging pulse is performed at time ( $t_{1-}$ ) immediately before the end ( $t_1$ ) of said discharging pulse.

7. Process according to Claim 5 or 6, which includes step (E3) for measuring current ( $I$ ) flowing through the battery at time ( $t_{id}$ ) close to the midpoint between the beginning ( $t_0$ ) and the end ( $t_1$ ) of said discharging pulse.

8. Process according to any one of Claims 5 to 7, which includes steps (E23, E34) for measuring voltage ( $U_t$ ) across the terminals of the battery at time ( $t_{0+}$ ) immediately after the beginning ( $t_0$ ) of said discharging pulse and at time ( $t_{ud}$ ) close to the midpoint between the beginning ( $t_0$ ) and the end ( $t_1$ ) of said discharging pulse.

9. Device for implementing the process according to any one of Claims 1 to 8 for measuring the charge state of battery ( $A_t$ ) to be tested by means of auxiliary generator ( $G$ ), characterized by the fact that it includes

- means (IC1 and/or IC2) for applying a charging current pulse to said battery from said auxiliary generator ( $G$ ),
- means (SH, CR, T) for regulating current ( $I$ ) flowing through the battery at constant value ( $I_0$ ) in such a way as to assert a constant current on the battery during said charging pulse, and
- means (CV, CA2, MC) for measuring voltage ( $U_t$ ) across the terminals of the battery for at least one predetermined time ( $t_{3-}$ ) during said charging pulse.

10. Device according to Claim 9, which also includes means (ID1, ID2) for applying a discharging current pulse to the battery from said auxiliary generator ( $G$ ), said regulating means (SH, CR, T) for asserting constant current ( $I_0$ ) in the battery during said discharging pulse, and said measuring means (CV, CA2, MC) for measuring said voltage across the terminals of the battery for at least one predetermined time ( $t_{1-}$ ) during said discharging pulse.

11. Device according to Claim 10, in which said auxiliary generator ( $G$ ) powers bridge circuit (CP) formed by four lateral branches and one diagonal branch, the diagonal branch includes said battery ( $A_t$ ), first lateral branch (B1-B3) includes first switch (IC1), second lateral branch (B1-B4) includes second switch (ID1) and discharging resistor ( $R_d$ ), third lateral branch (B2-B4) includes third switch (IC2) and charging resistor ( $R_c$ ), and fourth lateral branch (B2-B3) includes fourth switch (ID2), said first and third lateral branches form said means for applying a charging current pulse to battery ( $A_t$ ) from said auxiliary generator ( $G$ ) and carry current ( $I$ ) with said diagonal branch only during a charging pulse, said second and fourth lateral branches form

said means for applying a discharging current pulse to battery (At) from said auxiliary generator (G) and carry current (I) with said diagonal branch only during a discharging pulse.

12. Device according to any one of Claims 9 to 11, in which said means for regulating the current passing through the battery includes Hall probe (SH) connected in series with the battery and produces output voltage ( $U_H$ ) which depends on said current flowing through the battery, regulating circuit (CR) receives said output voltage ( $U_H$ ), and transistor (T) connected in series with said auxiliary generator (G) and its base current is controlled by said regulating circuit (CR) in response to the variations of said current flowing through the battery.

13. Device according to Claim 12, in which said regulating circuit (CR) includes, at the input, rectifying circuit (11) producing an output voltage equal to the absolute value of the output voltage of said Hall probe (SH).

14. Device according to Claim 12 or 13, in which said regulating circuit (CR) includes optoelectronic isolator (5).

15. Device according to any one of Claims 9 to 14, in which said means (CV) for measuring voltage ( $U_t$ ) across the terminals of the battery includes at least one optoelectronic isolator (CV3).

16. Device according to any one of Claims 9 to 15, which includes means (SH, CI) that is preferably galvanically isolated from said battery (At) and from said auxiliary generator (G) for measuring said current (I) flowing through the battery.



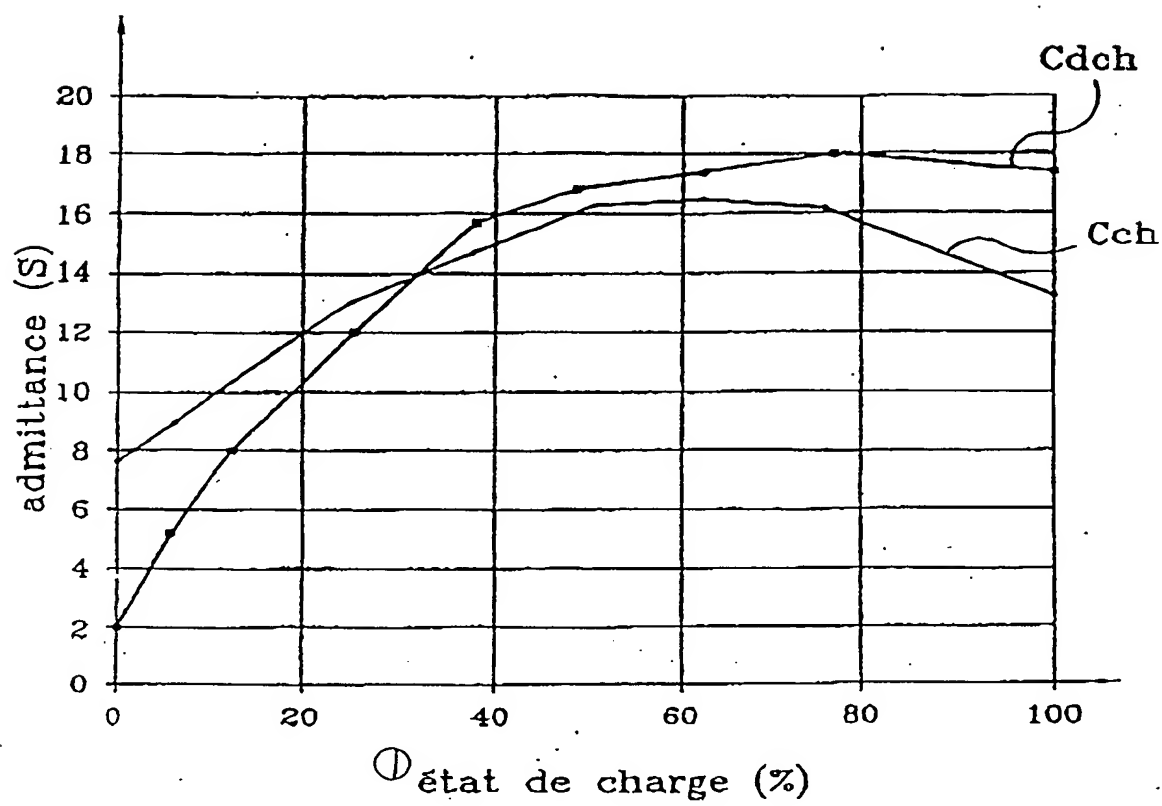
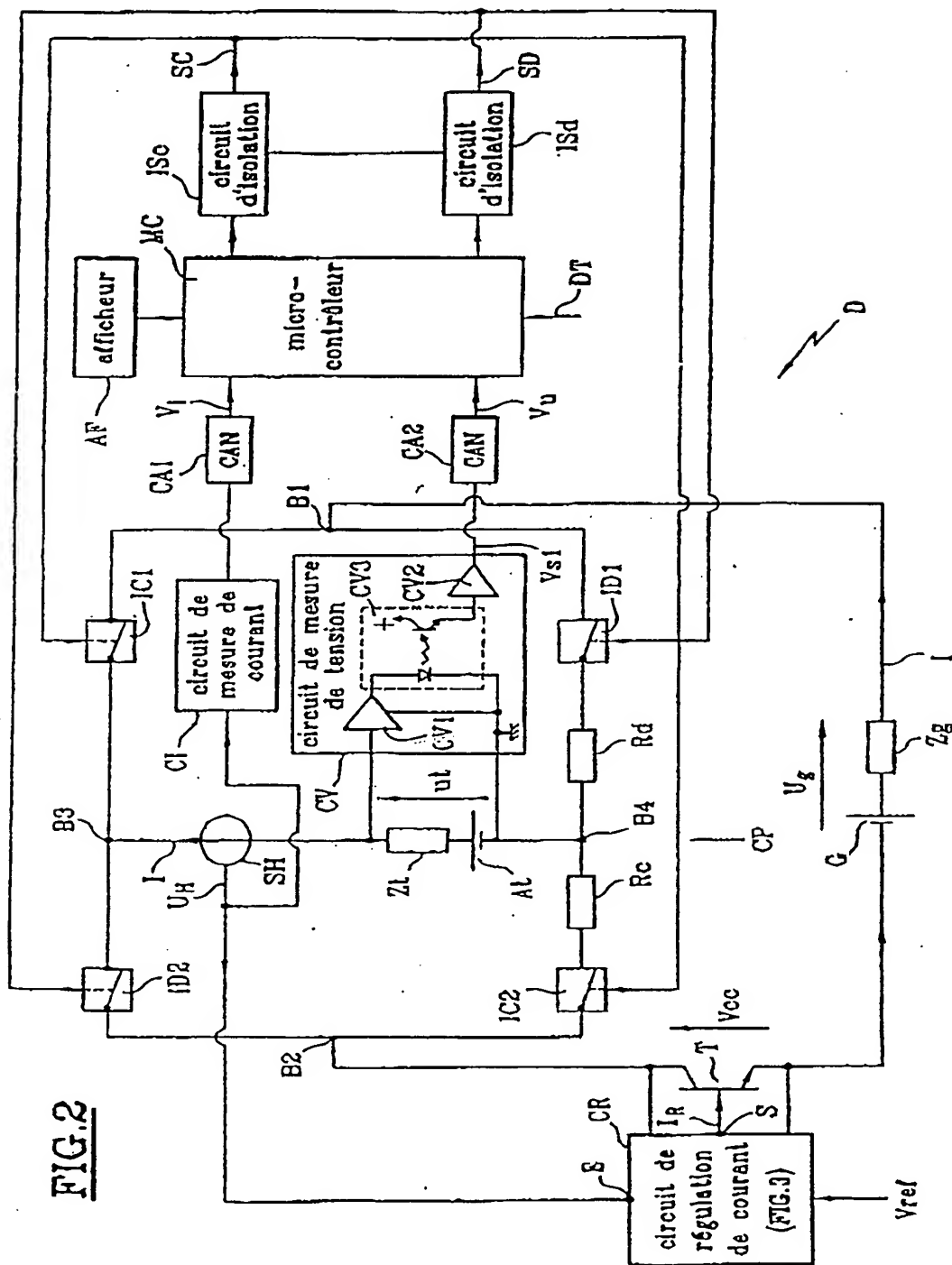


Figure 1

Key: 1 Charge state (%)



[Key to previous page:]

CI    Current measurement circuit  
AF    Display device  
MC    Microcontroller  
ISc, ISd    Isolation circuit  
CV    Voltage measurement circuit  
CR    Current regulating circuit (Figure 3)

[Key to previous page:]

CR	Current regulating circuit
1	Current sensor circuit
2	Subtractor
3	Error correction circuit
4	Adder
5	Optoelectronic isolator
6	Power amplifier
12	Amplifier

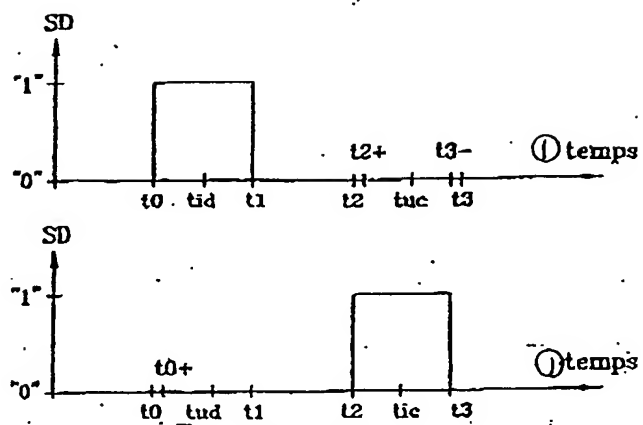


Figure 4A

Key: 1 Time

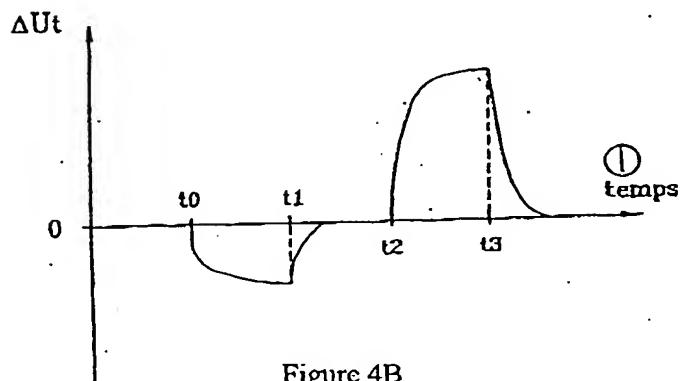


Figure 4B

Key: 1 Time

[Key to previous page:]

- A No
- B Yes
- E1 DT activated?
- E2 Discharging pulse at  $t_0$
- E23 Measurement of  $U_t$  at  $t_{0+}$
- E3 Measurement of  $I$  at  $t_{id}$
- E34 Measurement of  $U_t$  at  $t_{ud}$
- E4 Measurement of  $U_t$  at  $t_{1-}$
- E5 End of pulse at  $t_1$
- E6 Charging pulse at  $t_2$
- E67 Measurement of  $U_t$  at  $t_{2+}$
- E7 Measurement of  $I$  at  $t_{ic}$
- E78 Measurement of  $U_t$  at  $t_{uc}$
- E8 Measurement of  $U_t$  at  $t_{3-}$
- E9 End of pulse at  $t_3$
- E10 Determination of admittance and charge state values

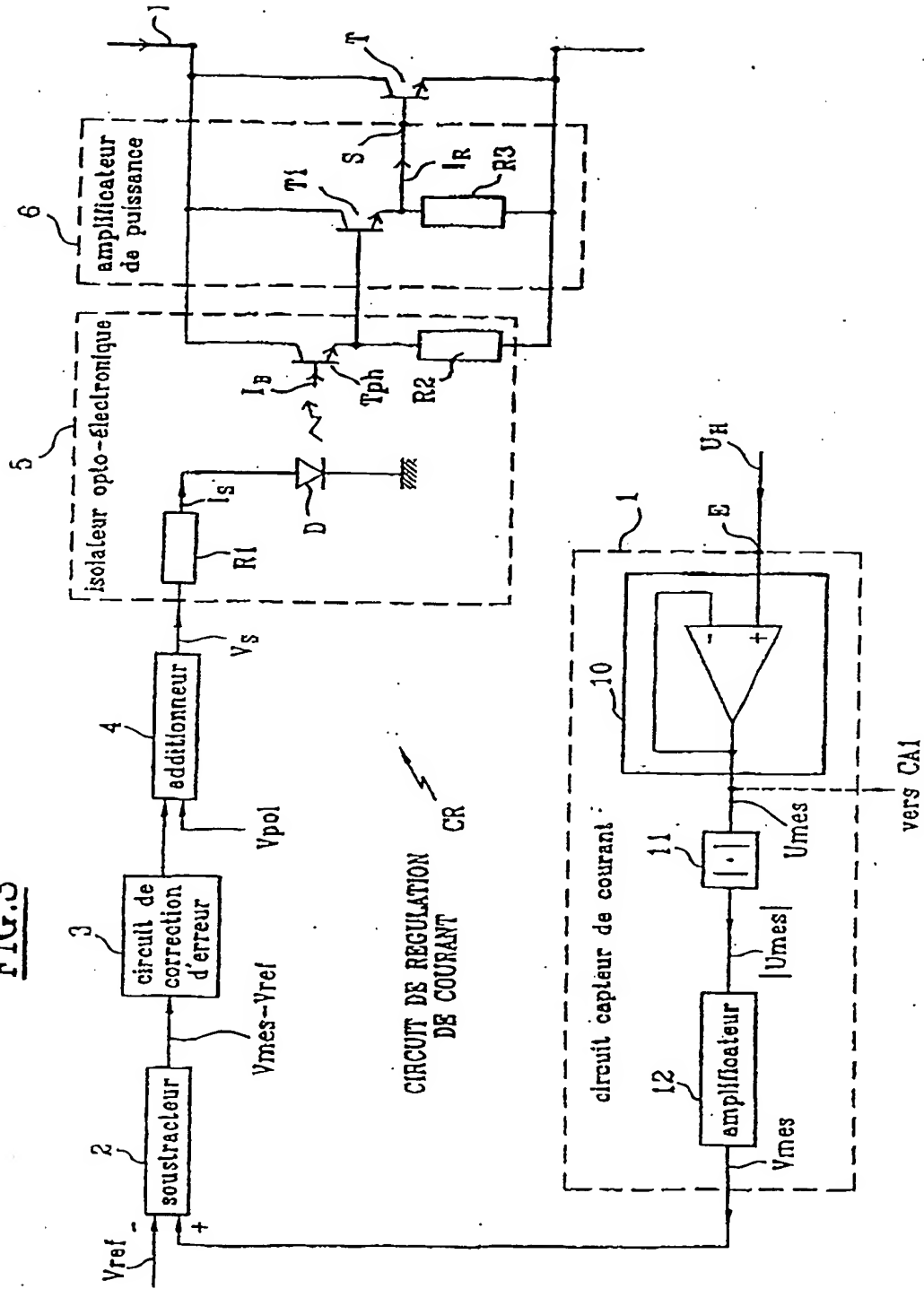
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FA 529150  
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**PRELIMINARY SEARCH REPORT**  
established on the basis of the most  
recent claims filed before the start  
of the search

DOCUMENTS CONSIDERED TO BE RELEVANT		Claims concerned in the examined document
Category	Citation of document with indication, where appropriate, of relevant passages	
X	EP 0 336 381 A (HABRA ELEKTRONIK GMBH) October 11, 1989 * abstract; figure * * column 5, line 29 – column 6, line 9 * * * column 7, line 5 – line 31 * * column 10, line 30 – line 34 *	1-16
Y	EP 0 549 464 A (ALCATEL N.V.) June 30, 1993 * abstract; figures * * column 1, line 24 – line 43 *	1-16
D	& FR 2 685 780 A	
Y	GB 2 275 118 A (HEWLETT PACKARD CO) August 17, 1994 * page 1, line 14 – line 32; claim 10; figures 2,4 * * page 9, line 8 – page 10, line 27 *	1-16
A	WO 96 05508 A (CHAMPLIN KEITH S) February 22, 1996 * page 6, line 3 – line 26; figures 1-4 *	1
A	EP 0 689 061 A (ALSTHOM CGE ALCATEL) December 27, 1995 * abstract; figures 5, 6 *	1
Date of completion of the search February 5, 1997		Examiner Fritz, S
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**FIG.3**





**FIG.5**

